

# Latency and Resolution Aware Task Offloading for Visual-based Assisted Driving

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### **Emerging Vehicular Applications**

#### **High Definition Maps**



#### See-Through

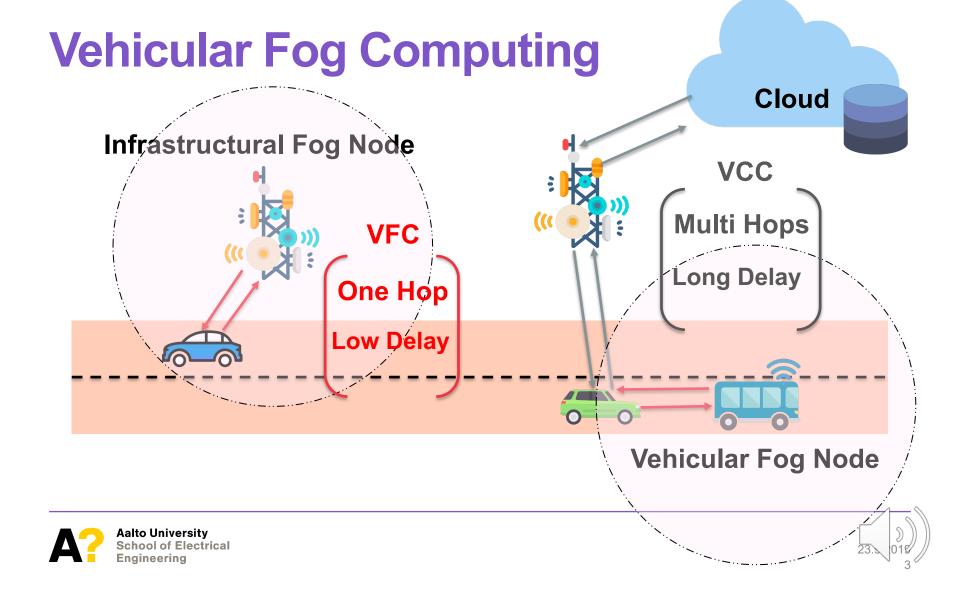


#### **Smart Lane Change**







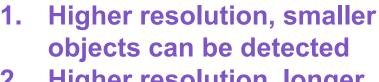


## **Task Offloading in VFC**





#### **Infrastructural Fog Node**



Higher resolution, longer latency (transmission latency and processing latency)



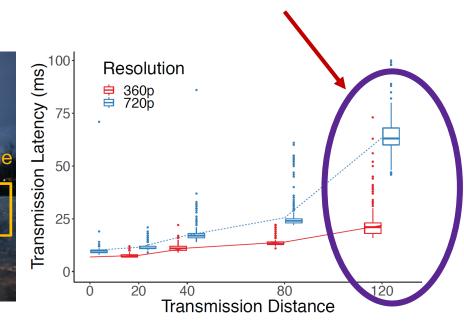
**Vehicular Fog Node** 





# Resolution v.s. Transmission Latency



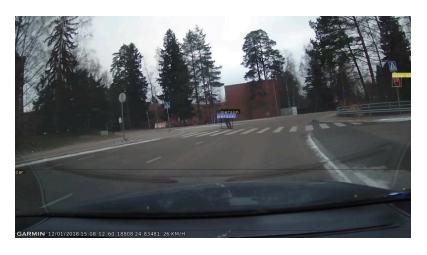


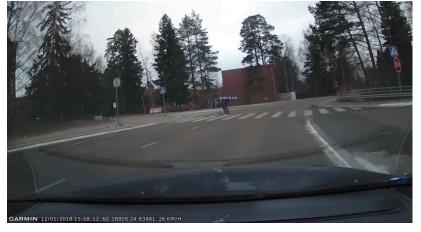
50ms





### Resolution v.s. Processing Latency

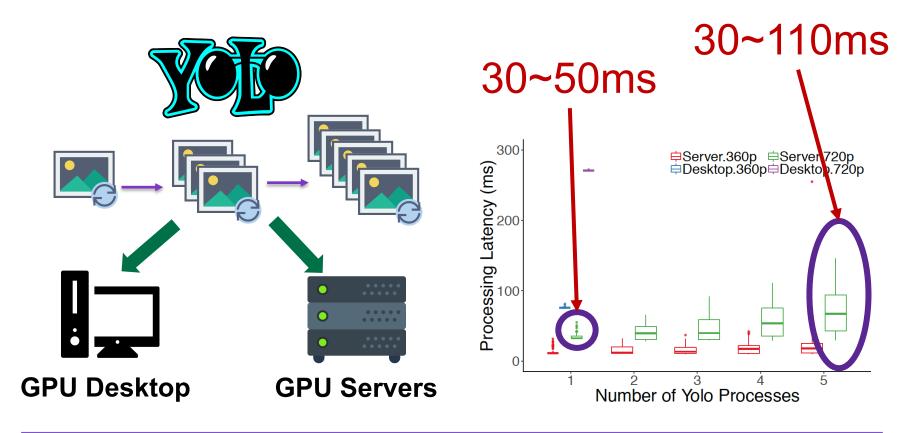




720p: 270ms

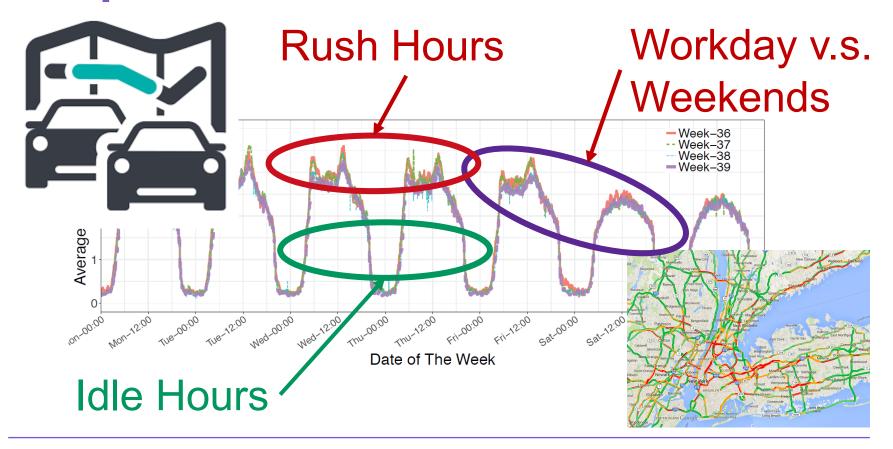
360p: 80ms

### Server Workload v.s. Processing Latency



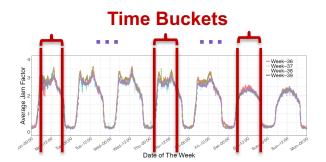


#### **Temporal Variation in Vehicular Traffic**





### **Server Workload Variation Modeling**



Divide one day in time buckets

Assumption: One type assisted driving application

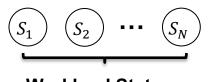


Number of neighboring vehicles



 $S_1$   $S_3$   $S_3$   $S_2$   $S_N$ 

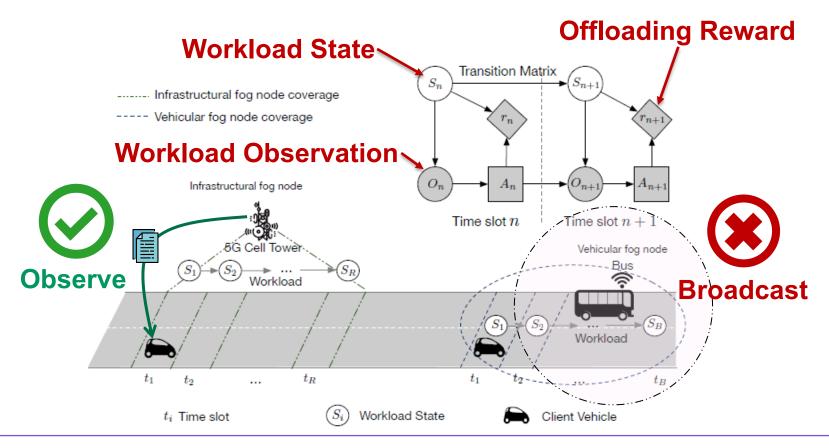
Monte Carlo



Record in each time slot

**Markov Chain** 

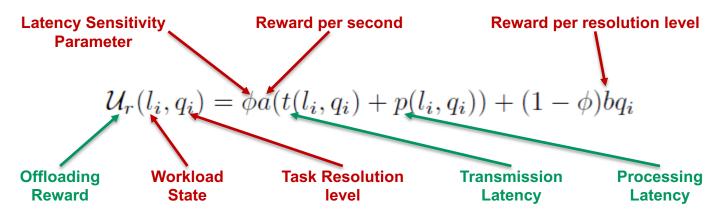
#### **Server Workload Observation**





## **Optimization Reward & Object**

#### **Reward for Each Task Offloading**



#### **Optimization Object:**

maximize the cumulative task reward during each time bucket

#### **Simulation Setup**



**Application Profiles (1 task/s)** 

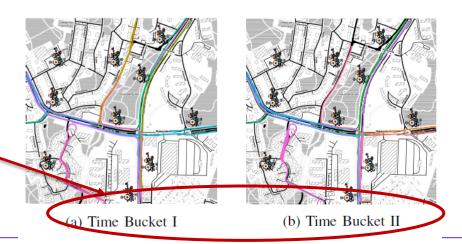


**Transmission Performance** 

**Two Time Buckets** 

I: 08:00~08:05

II: 20:00~20:05

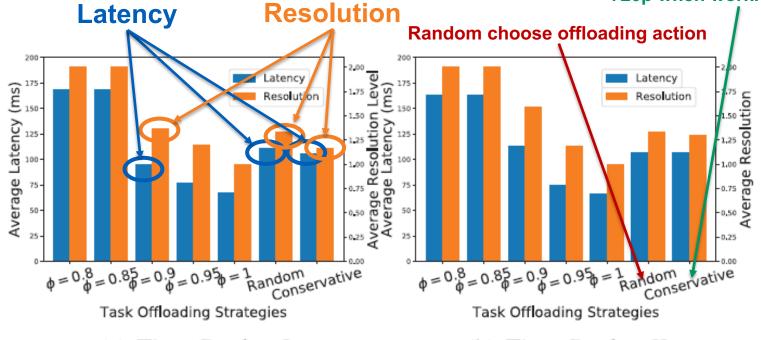




**Real-world Vehicle Trajectories** 

#### **Simulation Results**

Choose offloading 360p when workload is heavy and 720p when workload is light



(a) Time Bucket I

(b) Time Bucket II

## Q&A